

$$4.1 a) \quad \sigma = \pi (a_1 + a_2)^2 = 4\pi a^2 \quad a = 0.53 \text{ \AA}$$

$$\sigma = 3.53 \times 10^{-20} \text{ m}^2$$

$$b) \quad \text{speed } \langle v \rangle = \sqrt{\frac{8}{\pi} \frac{k_B T}{m}} = 797 \text{ m/s}$$

$$m = 1.66 \times 10^{-27} \text{ kg}$$

$$v_r \approx \sqrt{2} \langle v \rangle = 1124 \text{ m/s}$$

$$\bar{t} = \frac{1}{n \sigma v_r} = 5.04 \times 10^7 \text{ s}$$

$$c) \quad \lambda = \frac{1}{\sqrt{2} n \sigma} = 4.02 \times 10^{10} \text{ m}$$

$$4.2. \quad a) \quad \frac{dN}{dt} = -\phi A = -\frac{1}{4} \langle v \rangle n A = -\frac{1}{4} \langle v \rangle \frac{N}{V} A$$

$$pV = Nk_B T \quad p = \frac{Nk_B T}{V}$$

$$\frac{dp}{dt} = -\frac{1}{4} \frac{A}{V} \langle v \rangle p \quad \langle v \rangle = \sqrt{\frac{8}{\pi} \frac{k_B T}{m}}$$

$$b) \quad p = p_0 e^{-\frac{1}{4} \frac{A}{V} \langle v \rangle t}$$
$$= p_0 e^{-\frac{A}{V} t \sqrt{\frac{k_B T}{2\pi m}}}$$

4.3 a)

$$du_a = 2x dx + dy$$

$$\frac{\partial}{\partial y}(2x) = \frac{\partial}{\partial x}(1) = 0 \quad du_a \text{ exact}$$

$$du_b = y dx$$

$$\frac{\partial}{\partial y}(y) \neq \frac{\partial}{\partial x}(0) \quad du_b \text{ not exact}$$

b) $u_a(x,y) = x^2 + y + \text{const}$

c) $\frac{du_a}{I_1} = \int_0^2 dx \ 2x + \int_0^2 dy = 4 + 2 = 6$

$$I_2 = \int_0^2 dy + \int_0^2 dx \ 2x = 2 + 4 = 6$$

$$u_a(2,2) - u_a(0,0) = 6$$

du_b

$$I_1 = \int_0^2 0 dx + \int_0^2 0 dy = 0$$

$$I_2 = \int_0^2 0 dy + \int_0^2 2 dx = 4$$

integral over du_b depends on path